pbs-RPI-BBB

pbssoftLogic runtime for RPI and BeagleBoneBlack

Ver 1.0

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1. Installation

This document describes how to use pbsSoftLogic for the Raspberry PI and BeagleBone Blackboard Core CPU Board.

pbsSoftLogic can use the following RPI-BBB resources :

- GPIOs
- Watch Dog
- Serial Ports
- CAN IO Card with pbsCAN Protocols

Launch the Linux terminal and install the following software:

apt-get update apt-get install openssh-server

edit /etc/ssh/sshd_config by nano utility and change PermitRootLogin to yes: PermitRootLogin yes

Save the file and restart the RPI-BBB.

You can connect to the RPI-BBB using an SSH client software such as Putty and Filezilla. If you want to use Email Publishing Driver, SQLServer connection by TDS and MQTT in pbsSoftLogic, connect to RPI-BBB as root and install the following software, otherwise you do not need to install them.

```
for Email Publishing Driver install following modules on the RPI-BBB:
apt-get install curl
apt-get install python3-pycurl
apt-get install libcurl4-openssI-dev
```

for SQLite Driver install following modules on the RPI-BBB: apt-get install freetds-dev apt-get install freetds-bin

for MQTT Driver install following modules on the RPI-BBB:

apt-get install mosquitto-clients apt-get install mosquitto-dev apt-get install mosquitto apt-get install libmosquitto-dev

Unzip the pbsSoftLogic_ RPI64.zip folder, which is the pbsSoftLogic runtime kernel for RPI 64 Bit , and transfer it to the controller as follows:

Name	Date modified	Туре	Size
📒 etc	12/18/2024 10:54 AM	File folder	
📒 home	12/18/2024 10:56 AM	File folder	
🚞 mnt	12/18/2024 10:54 AM	File folder	
📔 readme.txt	12/20/2023 12:06 PM	TXT File	1 KB

Transfer content of the home folder to home folder of RPI-BBB:. Use filezilla Client for transferring to the controller.

When using filezilla, make sure the transfer type is set to binary, otherwise it will damage the transferred files. It is on Auto by default.

Settings			×
Settings Select page: Connection Connection SETP Active mode Passive mode FTP Proxy SETP Generic proxy Transfers File exists action Interface Passwords Themes Date/time format Filesize format File lists Language File editing File editing File editing File editing File editing File editing File editing File editing File editing File editing Date/secontations Updates Logging Debug	Default transfer typ Auto Auto ASCII Binary Automatic file type Treat the following ac am asp bat c cfm cgi conf Treat files witho V Treat files witho Treat dotfiles as Dotfiles are filenar	e classification filetypes as AS Add Remove ut extension as ASCII files nes starting wit	CII files: If you enter the wrong filetypes, those files may get corrupted when transferred.
OK Cancel			

In the home folder, you can see the following folders:

Name	Date modified	Туре
🧮 gspdata	9/27/2019 10:41 PM	File folder
📒 iecdata	11/11/2019 7:32 PM	File folder
늘 openvpn	9/27/2021 10:15 AM	File folder
늘 pbsLX	12/18/2024 10:57 AM	File folder
= sqldb	12/18/2024 10:54 AM	File folder
늘 sqlsynclog	9/27/2019 10:41 PM	File folder
늘 sqlsynclog2	9/27/2019 10:41 PM	File folder

The runtime core is the pbsLX folder. Other folders are for storing data if you are using some drivers.

For an explanation of the pbsLX folder, refer to the pbsSoftLogic user guide.

pbssoftLogic runtime requires ramdisk to run. So please create a folder in /mnt named ramdisk.



Using filezilla, edit the /etc/fstab file on RPI-BBB and add the following line to it:

LABEL=wri	table	1	ext4	defaults	0 0	
tmpfs	/mnt/	ramd	isk	tmpfs	rw,size=10M	0 0

This command will convert the /mnt/ramdisk folder as a real ramdisk in Linux.

In the unzipped pbsSoftLogic_ RPI64.zip folder, you can see the etc/init.d folder. Copy the /etc/init.d/xpsle file to the same path on the RPI-BBB.

Connect to the controller by putty utility by root user and execute following command :

chmod +x /etc/init.d/xpsle

In -s /etc/init.d/xpsle /etc/rc5.d/S97xpsle

This command executes pbsSLKLX, which is the pbsSoftLogic runtime kernel, at boot time.

You can run pbsSoftLogic kernel by adding these lines to /etc/rc.local file :

19 20 od /home/pbsLX 21 sh startup.sh 22 exit 0 23

You can restart the RPI-BBB. The pbsSoftLogic runtime is now ready to use.

2 – Programming

To use pbsSoftLogic IDE, please refer to pbsSoftLogic User Guide. In this section, we will explain the local IO for RPI-BBB.

In pbsSoftLogic, Local IO is a driver that manages all the resources placed on the main CPU, such as LED, GPIO, Modem, Watch dog, etc. If you want to use RPI or BBB to test and learn pbsSoftLogic, you don't need to define Local IO for your project.

👸 File Edit Project View	ools Help
D 🚅 🖬 🐰 🖳 🛤 💼	
f 🐼 FB List 🔗	MainPOU
Føl List > → FBList → → Comment → → Comment → → Contentine → → Constantine → → GobalVar/uput → → LauDP2 → → LauDP2 → → NiGC → → Protocols → → Timers → → Counters → → Digical → → Process → → HPFunctions →	MainPOU
	Save Exit Controller Controller Controller

Run pbsSoftLogic and create a new project and open the project settings.

Select GeneralBeagleBone as the RTU type and enter the controller IP address.

Right-click on the list of drivers and add a new Local_IO to the project and name it LIO.

Options							-	×
General Time Setting L	AN Setting Stats License Kernel			Drivers	List			
Logic Scan Time(ms)	100	⊳	Name LIO	Path \LIO	Type LOCAL_IO	Enable		
RTU	GeneralBeagleBone 💌							
RTU IP	192 168 1 117							
Save	Exit	_	Reset Controller	Delete Logic	Delete Configuratio	'n		

Double-click on LIO Driver and you will see the following screen:

🚽 pbsSoftLogic Editor	
-----------------------	--

File

Options

```
<?xml version="1.0"?>
<OPCSrvTags>
    <Version>1.0.0</Version>
    <Tag Name="SYS.Reset" Type="SYS" Init="0" Address="0" />
    <Tag Name="SYS.WDTEnable" Type="SYS" Init="60" Address="1" />
    <Tag Name="SYS.ModemPW" Type="SYS" Init="0" Address="2" />
    <Tag Name="SYS.ResetFactory" Type="SYS" Init="0" Address="3" />
    <Tag Name="SYS.ModemConnectCmd" Type="SYS" Init="0" Address="4" />
     <Tag Name="SYS.ModemConnected" Type="SYS" Init="0" Address="5" />
    <Tag Name="SYS.ModemRSSI" Type="SYS" Init="0" Address="6" />
    <Tag Name="GPIO DI1" Type="DI" Init="0" Address="1" />
    <Tag Name="GPIO DI2" Type="DI" Init="0" Address="2" />
    <Tag Name="GPIO DI3" Type="DI" Init="0" Address="3" />
    <Tag Name="GPIO DI4" Type="DI" Init="0" Address="4" />
    <Tag Name="GPIO DI5" Type="DI" Init="0" Address="5" />
    <Tag Name="GPIO DI6" Type="DI" Init="0" Address="6" />
    <Tag Name="GPIO DI7" Type="DI" Init="0" Address="7" />
    <Tag Name="GPIO DI8" Type="DI" Init="0" Address="8" />
    <Tag Name="GPIO DO1" Type="DO" Init="0" Address="1" />
    <Tag Name="GPIO DO2" Type="DO" Init="0" Address="2" />
    <Tag Name="GPIO DO3" Type="DO" Init="0" Address="3" />
    <Tag Name="GPIO DO4" Type="DO" Init="0" Address="4" />
    <Tag Name="GPIO DO5" Type="DO" Init="0" Address="5" />
    <Tag Name="GPIO DO6" Type="DO" Init="0" Address="6" />
    <Tag Name="GPIO DO7" Type="DO" Init="0" Address="7" />
     <Tag Name="GPIO DO8" Type="DO" Init="0" Address="8" />
</OPCSrvTags>
```

You can use the above tags in your logic:

SYS.Reset : when SYS.Reset set to 1 , for value more than watch dog time , will reset RPI-BBB.

SYS.WDTEnable : if set Init to 0 , WDT is disabled , when set to 60 for defining 60 sec WDT . If you need more WDT time, increase this value.

SYS.ModemPW: You can consider a 4G modem for your board and connect its power to GPIO and turn the modem on/off from the program. If set to 0, it means you don't have a modem on the board, otherwise the GPIO number should be set to SYS.ModemPW for the initial value.

SYS.ResetFactory : You can consider a GPIO as a factory reset button to delete the pbsSoftLogic logic and configuration files. Every time you press the Factory Reset button and hold it for more than 10 seconds, the LocalIO Driver deletes the configuration and logic files.

If the initial value is set to 0, it means you do not have the Factory Reset button; otherwise the GPIO number should be set as the initial value.

SYS.ModemConnectCMD : Changing from 0 to 1 turns the modem on and tries to connect to the mobile network. Changing from 1 to 0 turns the modem off.

SYS.ModemConnected: When it changes to 1, it indicates that the modem is properly connected to the network.

SYS.ModemRSSI : Shows Modem RSSI signal .

You can design up to 64 GPIOs as digital inputs or outputs on your board. To configure the GPIO software on your RPi or BBB, you should refer to their manual. We assume that you have configured the GPIOs and have one number for each GPIO.

If you don't have GPIO on your board that you want to be controlled by pbsSoftLogic, set all initial values for signals of type DI/DO to 0.

Otherwise you can add or remove tags from the GPIO list. You can change the name and set the initial value to the GPIO number. The tag address must be unique for each DI or DO type.

Suppose you have four GPIOs as DI with GPIO numbers 5,6,7,8 and two LEDs with GPIO numbers 10,11. The GPIO list will be as follows:

```
File
Options
  <?xml version="1.0"?>
  <OPCSrvTags>
       <Version>1.0.0</Version>
       <Tag Name="SYS.Reset" Type="SYS" Init="0" Address="0" />
       <Tag Name="SYS.WDTEnable" Type="SYS" Init="60" Address="1" />
       <Tag Name="SYS.ModemPW" Type="SYS" Init="0" Address="2" />
       <Tag Name="SYS.ResetFactory" Type="SYS" Init="0" Address="3" />
       <Tag Name="SYS.ModemConnectCmd" Type="SYS" Init="0" Address="4" />
       <Tag Name="SYS.ModemConnected" Type="SYS" Init="0" Address="5" />
       <Tag Name="SYS.ModemRSSI" Type="SYS" Init="0" Address="6" />
       <Tag Name="GPIO_DI1" Type="DI" Init="5" Address="1" />
       <Tag Name="GPIO DI2" Type="DI" Init="6" Address="2" />
       <Tag Name="GPIO DI3" Type="DI" Init="7" Address="3" />
       <Tag Name="GPIO DI4" Type="DI" Init="8" Address="4" />
      <Tag Name="LED RUN" Type="DO" Init="10" Address="1" />
      <Tag Name="LED ERR" Type="DO" Init="11" Address="2" />
  </OPCSrvTags>
```

Now suppose you want to create a pulse generator and connect it to the Run LED. From the Timer Function Blocks, drag and drop a PulseGen function and place it on the MainPOU.

	- ° ×
	_ 6
	× POUs
CAT Bill True True PuissGen CAT Tris Tris	 ♥ FB Instances ♥ Comments ♥ Vers ♥ Inputs ♥ Outputs ♥ Properties ♥ I ♥ Appearance Figure None EditPorts ■ LetPorts ¶ I ● Y Appearance Figure None EditPorts I LetPorts ¶ I ■ Y Appearance Figure None EditPorts I LetPorts ¶ I ■ None <
	CAT THE THE CAT THIS CAT THIS

Drag a Constant Bool and connect to Trg input of PulseGen FB.

Drag a constant time and connect to Time input of Pulsegen FB.

Drag an OutputSignal and connect to Q Output of FB.

Save the project and transfer the Logic and Configuration to the RPI-BBB and restart it.





It takes 40 seconds for the RPI-BBB to boot and run the pbsSoftlogic runtime kernel. After that, you can connect to it and monitor your logic.

Click on connect to controller button and it will monitor your logic.



And the RPI_BB if you setup GPIOs properly, RUN LED flashes on and off every second.

In pbsSoftLogic, the default password for root is root. But if you change it, you need to change it in the tools option menu.

CNT B#True	1.000000	Time Pulse	ers Gen	,	DDV	_
	💀 pbsSoftLogic Op	tions	Q •			Run
CNT T#1s	FB Back Color LMP FB Back Color	FB Back Co	lor V			
	FTP/SFTP Port	22	Enable Encryption			
	☑ Use SSH	,	Encryption Key(16 char)			
	Linux User	root				
	User Password					
	LMP Time (msec)	20001				
			Ok			

After changing the password, close and re-run pbsSoftLogic IDE.

3- Protocol Configuration

To use protocols such as Modbus, DNP3, IEC104, MQTT, ... you need to add the appropriate driver to your project. For detailed explanations, please refer to the pbsSoftLogic user guide. In This section shows the serial port settings.

When you want to use serial ports in pbsSoftLogic, you need to use the serial port names.

From BeagleBone Black Manual :

The BeagleBone Black has four serial port UARTs, which are named /dev/ttyO1, /dev/ttyO2, /dev/ttyO4, and /dev/ttyO5. Each UART connects to a receiver (RX) and transmitter (TX).

Suppose you want to define a Modbus Master for the UART1 of BBB for the project.

Right-click in the driver list and add Modbus Master Driver. For example, name it MM1.

🖳 Options								- 0	\times
General Time Setting LA	AN Setting Stats License Kernel								
				Drivers	s List				
			Name	Path	Туре	Enable			
Logic Scan Time(ms)	100	▶	LIU	NLIU	LUCAL_IU				
			_						
			🖳 pb	sSoftLogic	: New Driver			×	
RTU	GeneralBeagleBone 💌								
			D	river	Modbus	Master	•		
					,				
RTU IP	192 168 1 117		N	lame	MM1				
			- Ir	nstance	1				
					Ma	ke Driver			
								1	
1	1	в	eset	Delete	Delete	1			
Save	Exit	Co	ntroller	Logic	Configurati	on			

Add One Modbus Slave Driver and name it MS1.

🛃 Options						_	\times
General Time Setting L	AN Setting Stats License Kernel						
			Drivers	List			
		Name	Path	Туре	Enable		
Logic Scan Time(ms)	100			LULAL_IU ModbusMaster			
					-		
		💀 pbsSoftLog	c New Driver			×	
RTU	GeneralBeagleBone 💌						
		Driver	Modb	usSlave	•		
			,				
RTU IP	192 168 1 117	Name	MS1				
		Instance	1			_	
				Make Driver			
			ų				
						1	
1		Passt	Delete	Delete	1		
Save	Exit	Controller	Logic	Configuration			

Keep the instance number 1 for both drivers. The instance number must be unique for a driver type. If you want to add another Modbus Master to the project, you must change the instance to 2 for the second driver.

Double-click on MM1 Driver and you will see the following screen:

pbsSoftLogic Modbus Master Edito	r	- a
tions Blocks Toos Help		
, biesits rage rist		<pre></pre> < 27xml version="1.0"?>
Physical Layer	Serial ~	<pre></pre> (Options) (Version)1.0.0//Version)
Corial		(Note: Section of Sect
Seria		<pre><dkame>PhysicalLayer</dkame></pre> /Vame>
COM Port Name	/dev/ttyO1	<value>#8232</value>
Baud Rate	9600 ~	<name>COMPort</name>
Data Bit	0	<pre></pre> <description display="</p"></description>
Duid Di	0 ~	
Stop Bit	1 ×	<pre>(Node) (Name>COIPortName</pre>
Parity	Mana	<pre><pre>desc:Serial Port Nume for Communication , if Blank Use COMPort Nums/Desc></pre></pre>
. any	None	
		All of the second se
TCP		<pre></pre>
		<pre></pre>
TCP Port	502	
		<pre>diame>late1t://inme> //actions/late1te/latence</pre>
		<pre></pre> <
Continuous Poll	True V	
		<pre></pre>
DiagMode	False ~	<pre>deacy1_2</pre> deacy1_2 deacy1_2
Write By Change	Terre	
tine by onange	True	<node></node>
Enable Buffering	False V	<pre></pre> < description:
Instance	1	Ande>
		Change That same
WakeUp String		<pre><pre>cdtabatece values</pre></pre>
	Update	Chame> TCPPort
		(Desc) TCPPort(/Desc)
		(d)ode> (d)one>(ont Poll (/Name))
		<pre></pre> demonstrate of the second
		<pre></pre>
		(Node>
		diame>WakeDpString <pre>deactylil send to mothing alayse for waking up device for communication .Only support for 28212 Mode CompOsite was he 0 and Dolling constr.</pre>
		Value /> (Value />

You need to use the serial port name as the COM port name and set the other parameters.

Likewise, you should use the serial port name as the COM port name for modbus Slave Driver.

pbsSoftLogic Modbus Slave Editor (C:\PIP2025\pbsSoftLogic\PSLE\Sample\RPI_BBB\MS1)* -				
File Edit Help			🛃	Modbus
Click here to add filter criteria				
Parameters Tags				
Physical Layer	TCP Configuration —		General Configuration	
• Serial O TCP	TCP Port	502	Slave Address	3 *
Serial Configuration			Timeout (s)	20
Com port COM1	✓ Protocol	RTU ~	Physical Layer Scan Time (ms)	100
Com port Name /dev/ttyO2	Flow Control	None ~	Instance	1 ~
Baud Rate 9600	✓ Stop Bits	1 ~	Diagnostic Mode	False ~
Data Bit 8	✓ Parity	None ~		

For protocol configuration details, please refer to the pbsSoftLogic user guide for each protocol.

If you want to connect a modem to your board, you need to rename the modem serial port to /dev/ttyModem . You can do this by editing the /etc/udev/rules.d folder and adding a new rule to rename the modem serial port like the following example:

SUBSYSTEM=="tty" ACTION=="add", KERNEL=="ttyUSB[0-9]*", ATTRS{idVendor}=="05c6", ATTRS{idProduct}=="9090", ENV{ID_USB_INTERFACE_NUM}=="03", SYMLINK+="ttyModem "